

# Planetary Gearheads

## 0,1 Nm

For combination with  
DC-Micromotors  
Brushless DC-Motors  
Stepper Motors

### Series 10/1

	10/1	10/1K
Housing material	metal	metal
Geartrain material	steel	steel
Recommended max. input speed for:		
– continuous operation	5 000 rpm	5 000 rpm
Backlash, at no-load	$\leq 3^\circ$	$\leq 3^\circ$
Bearings on output shaft	sintered bearings	ball bearings, preloaded
Shaft load, max.:		
– radial (5 mm from mounting face)	$\leq 1$ N	$\leq 7$ N
– axial	$\leq 2$ N	$\leq 5$ N
Shaft press fit force, max.	$\leq 10$ N	$\leq 5$ N
Shaft play		
– radial (5 mm from mounting face)	$\leq 0,04$ mm	$\leq 0,02$ mm
– axial	$\leq 0,1$ mm	$= 0$ mm
Operating temperature range	$-30 \dots +100^\circ\text{C}$	$-30 \dots +100^\circ\text{C}$

### Specifications

		1	2	3	4	5	6
Number of gear stages		1	2	3	4	5	6
Continuous torque	mNm	5	15	54	100	100	100
Intermittent torque	mNm	200	200	200	200	200	200
Weight without motor, ca.	g	6	7	8	10	11	13
Efficiency, max.	%	90	80	70	60	55	48
Direction of rotation, drive to output		=	=	=	=	=	=
Reduction ratio (exact)		4:1	16:1	64:1	256:1	1 024:1	4 096:1
L2 [mm] = length without motor		9,7	12,8	15,9	19,0	22,1	25,2
L1 [mm] = length with motor							
	1016M...G	25,4	28,5	31,6	34,7	37,8	40,9
	1024M...S	33,4	36,5	39,6	42,7	45,8	48,9
	1219M...G	28,4	31,5	34,6	37,7	40,8	43,9
	1224M...S	33,9	37,0	40,1	43,2	46,3	49,4
	1224M...SR	33,9	37,0	40,1	43,2	46,3	49,4
	1226M...B	35,7	38,8	41,9	45,0	48,1	51,2
	ADM1220...-05	27,1	30,2	33,3	36,4	39,5	42,6
	ADM1220...-55	27,1	30,2	33,3	36,4	39,5	42,6
	AM0820...-10	23,5	26,6	29,7	32,8	35,9	39,0
	AM1020...-08	25,6	28,7	31,8	34,9	38,0	41,1

