

Brushless DC-Servomotors

sensorless, with optional Hall Sensors
SMARTSHELL® Technology

2,1 mNm

For combination with
Gearheads:
15/5(S), 15/8, 16/7
Drive Electronics:
Speed Controller

Series 1524 ... BSL

	1524 U	006 BSL	009 BSL	012 BSL	
1 Nominal voltage	U_N	6	9	12	Volt
2 Terminal resistance, phase-phase	R	4,30	9,7	15,3	Ω
3 Output power ¹⁾	$P_{2 \text{ max.}}$	8	8	8	W
4 Efficiency	$\eta_{\text{ max.}}$	54	53	54	%
5 No-load speed	n_o	18 500	19 200	19 900	rpm
6 No-load current (with shaft \varnothing 2,0 mm)	I_o	0,110	0,078	0,062	A
7 Stall torque	M_H	4	4	4	mNm
8 Friction torque, static	C_o	0,140	0,140	0,140	mNm
9 Friction torque, dynamic	C_v	$9,5 \cdot 10^{-6}$	$9,5 \cdot 10^{-6}$	$9,5 \cdot 10^{-6}$	mNm/rpm
10 Speed constant	k_n	3 339	2 318	1 805	rpm/V
11 Back-EMF constant	k_E	0,299	0,431	0,554	mV/rpm
12 Torque constant	k_M	2,86	4,12	5,29	mNm/A
13 Current constant	k_i	0,350	0,243	0,189	A/mNm
14 Slope of n-M curve	$\Delta n / \Delta M$	5 020	5 457	5 221	rpm/mNm
15 Terminal inductance, phase-phase	L	82	169	273	μH
16 Mechanical time constant	τ_m	15	16	16	ms
17 Rotor inertia	J	0,30	0,30	0,30	gcm^2
18 Angular acceleration	$\alpha_{\text{ max.}}$	129	123	133	$\cdot 10^3 \text{ rad/s}^2$
19 Thermal resistance	$R_{\text{th} 1} / R_{\text{th} 2}$	2,6 / 29,0			K/W
20 Thermal time constant	τ_{w1} / τ_{w2}	1 / 326			s
21 Operating temperature range		- 30 ... +125			$^{\circ}\text{C}$
22 Shaft bearings		ball bearings, preloaded			
23 Shaft load max.:					
– radial at 3 000/20 000 rpm (4,5 mm from mounting flange)		5 / 4 for series 1524 U ... B ..			N
– radial at 3 000/20 000 rpm (2,0 mm from mounting flange)		5,5 / 4,5 for series 1524 E ... B ..			N
– axial at 3 000/20 000 rpm (push-on only)		4 / 3,5			N
– axial at standstill (push-on only)		17			N
24 Shaft play:					
– radial	\leq	0,015			mm
– axial	$=$	0			mm
25 Housing material		mounting face in aluminium, housing in plastic			
26 Weight		20			g
27 Direction of rotation		electronically reversible			
Recommended values - mathematically independent of each other					
28 Speed up to ²⁾	$n_{e \text{ max.}}$	62 000	62 000	62 000	rpm
29 Torque up to ^{1) 2)}	$M_{e \text{ max.}}$	2,1	2,0	2,1	mNm
30 Current up to ^{1) 2)}	$I_{e \text{ max.}}$	0,91	0,61	0,48	A

¹⁾ at 36 000 rpm

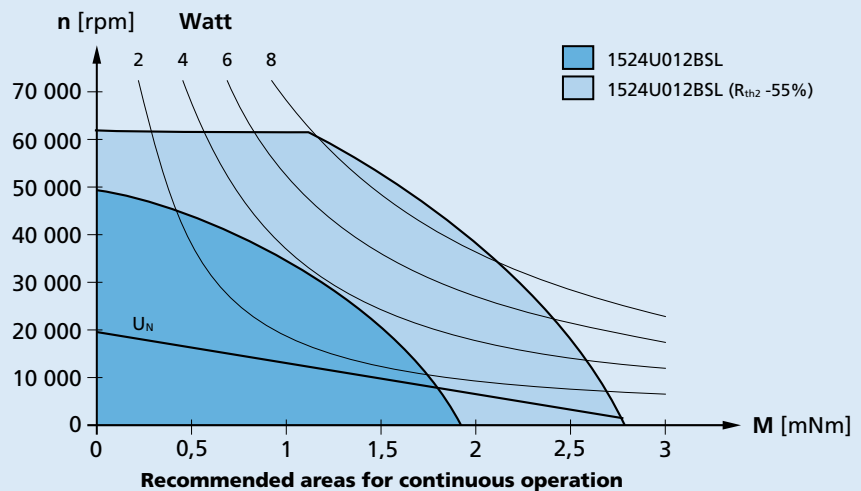
²⁾ thermal resistance $R_{\text{th} 2}$ by 55% reduced

Note:

The diagram indicates the recommended speed in relation to the available torque at the output shaft for a given ambient temperature of 22°C.

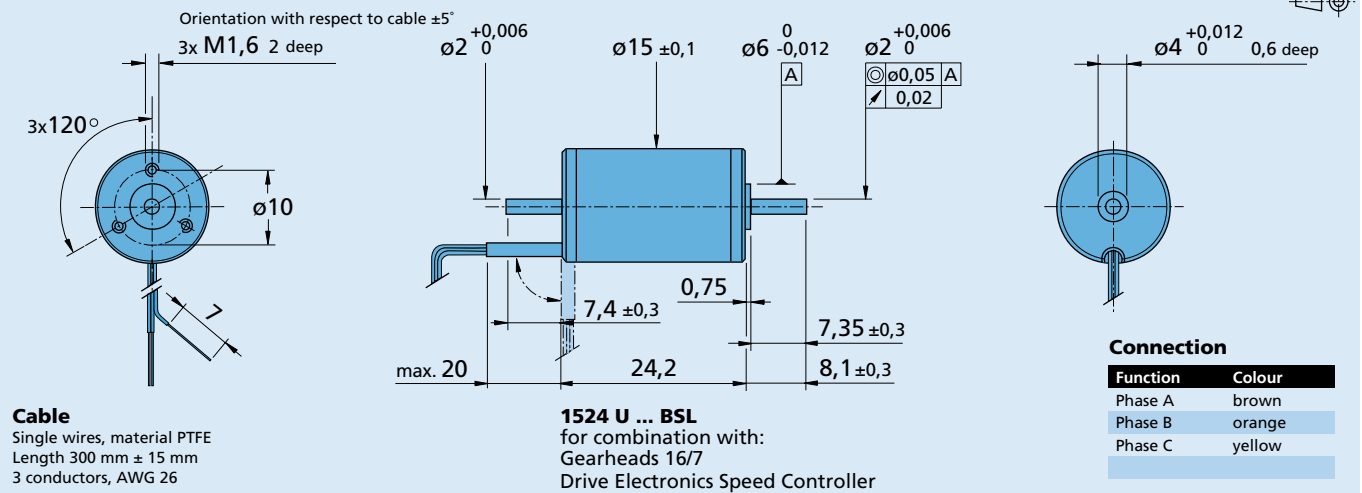
The diagram shows the motor in a completely insulated as well as thermally coupled condition ($R_{\text{th} 2}$ 55% reduced).

The nominal voltage (U_N) curve shows the operating point at nominal voltage in the insulated and thermally coupled condition. Any points of operation above the curve at nominal voltage will require a higher operating voltage. Any points below the nominal voltage curve will require less voltage.

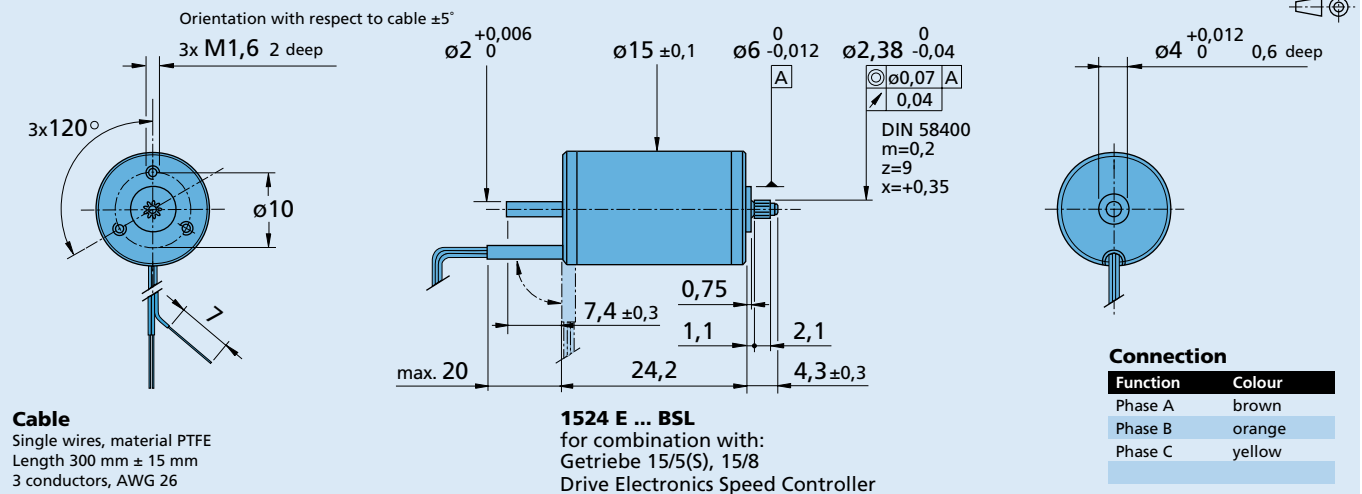


Options
 Motors with digital sensors:
 1524 U ... BDS, 1524 E ... BDS
 Motors with analog sensors:
 1524 U ... BAS, 1524 E ... BAS

1524 U ... BSL sensorless



1524 E ... BSL sensorless



1524 U ... BAS, 1524 U ... BDS, 1524 E ... BAS, 1524 E ... BDS with Hall sensors

