

# Flat DC-Micromotors

## Precious Metal Commutation

# 3,4 mNm

### Series 2607 ... SR

Values at 22°C and nominal voltage		2607 T	006 SR	012 SR	024 SR	
1	Nominal voltage	$U_N$	6	12	24	V
2	Terminal resistance	R	8,2	36,5	128	$\Omega$
3	Output power	$P_{2nom.}$	1,08	0,97	1,1	W
4	Efficiency, max.	$\eta_{max.}$	81	80	81	%
5	No-load speed	$n_0$	6 600	5 900	6 200	rpm
6	No-load current, typ. (with shaft $\varnothing$ 1,5 mm)	$I_0$	0,007	0,004	0,002	A
7	Stall torque	$M_H$	6,26	6,21	6,77	mNm
8	Friction torque	$M_R$	0,06	0,07	0,07	mNm
9	Speed constant	$k_n$	1 111	500	261	rpm/V
10	Back-EMF constant	$k_E$	0,9	2	3,83	mV/rpm
11	Torque constant	$k_M$	8,59	19,09	36,54	mNm/A
12	Current constant	$k_I$	0,116	0,052	0,027	A/mNm
13	Slope of n-M curve	$\Delta n/\Delta M$	1 055	957	917	rpm/mNm
14	Rotor inductance	L	465	2 200	8 400	$\mu H$
15	Mechanical time constant	$\tau_m$	7,5	6,8	6,5	ms
16	Rotor inertia	J	0,68	0,68	0,68	gcm <sup>2</sup>
17	Angular acceleration	$\alpha_{max.}$	92	92	100	$\cdot 10^3 \text{rad/s}^2$
18	Thermal resistance	$R_{th1} / R_{th2}$	2,7 / 24,45			K/W
19	Thermal time constant	$\tau_{w1} / \tau_{w2}$	1,8 / 163			s
20 Operating temperature range:						
– motor			-25 ... +80			°C
– winding, max. permissible			+100			°C
21 Shaft bearings						
22 Shaft load max.:			sintered bearings (standard)	ball bearings, preloaded (optional version)		
– with shaft diameter			1,5	1,5		mm
– radial at 3 000 rpm (3 mm from bearing)			1,2	5		N
– axial at 3 000 rpm			0,2	0,5		N
– axial at standstill			20	10		N
23 Shaft play						
– radial		$\leq$	0,03	0,015		mm
– axial		$\leq$	0,2	0		mm
24	Housing material		plastic			
25	Mass		16,1			g
26	Direction of rotation		clockwise, viewed from the front face			
27	Speed up to	$n_{max.}$	8 000			rpm
28	Number of pole pairs		2			
29	Magnet material		NdFeB			
<b>Rated values for continuous operation</b>						
30	Rated torque	$M_N$	3,2	3,1	3,4	mNm
31	Rated current (thermal limit)	$I_N$	0,4	0,17	0,1	A
32	Rated speed	$n_N$	2 500	2 500	2 500	rpm

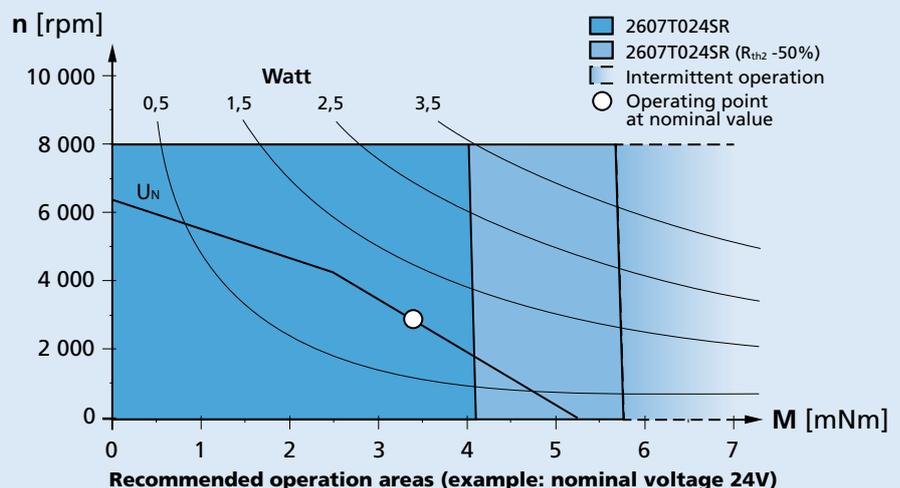
**Note:** Brush plate is loose and is only held in place by magnetic force.  
 Rated values are calculated with nominal voltage and at a 22°C ambient temperature. The  $R_{th2}$  value has been reduced by 0%.

**Note:**

The diagram indicates the recommended speed in relation to the available torque at the output shaft for a given ambient temperature of 22°C.

The diagram shows the motor in a completely insulated as well as thermally coupled condition ( $R_{th2}$  50% reduced).

The nominal voltage ( $U_N$ ) curve shows the operating point at nominal voltage in the insulated and thermally coupled condition. Any points of operation above the curve at nominal voltage will require a higher operating voltage. Any points below the nominal voltage curve will require less voltage.



**Dimensional drawing**

