## Accessories

| Adapter board BX4 CxD | For combination with Brushless DC-Servomotos with integrated Motion Controller: 2232...BX4 CxD, 2250...BX4 CxD |  |
| :---: | :---: | :---: |
| Part No.: 6501.00113 |  |  |
|  | 6501.00113 |  |
| Temperature range: |  |  |
| - Operating temperature | $-10 \ldots+65$ | ${ }^{\circ} \mathrm{C}$ |
| Dimension and Weight: |  |  |
| - Dimension (L x B x H) | $60 \times 50 \times 15$ | mm |
| - Weight | 30 | g |

Note: All switches are in the "OFF" position in the as-delivered condition. These switches must be set accordingly depending on the application.

## General information

The adapter board is used to connect Brushless DC-Servomotors with integrated Motion Controller and a serial RS232 or CAN interface.
The different operating modes can be selected using the 6 DIP switches.
A Brushless DC-Servomotor with integrated Motion Controller can be connected to each adapter board.

Description of DIP switch (S1) settings

| 1: Fault | ON | Pull-up resistor with LED connected to adapter board. |
| :--- | :--- | :--- |
|  | OFF | Open collector |


| Pin Connection X1 | Pin Connection X2 |
| :---: | :---: |
| 1 3. In | 1 3. In |
| $2+24 \mathrm{~V}$ | $2+24 \mathrm{~V}$ |
| 3 GND | 3 GND |
| 4 An In | 4 An In |
| 5 AGND | 5 AGND |
| 6 Fault | 6 Fault |
| 7 RS-232 RxD / CAN-L | 7 RS-232 RxD / CAN-L |
| 8 RS-232 TxD / CAN-H | 8 RS-232 TxD / CAN-H |
|  | 9 n.c. |
|  | 10 n.c. |

## at RS232 operation ${ }^{1)}$

 Pin Connection $\times 3$2 RS-232/RxD
3 RS-232/TxD
5 GND

| Pin Connection X4 | LED |
| :--- | :--- |
| 1 | Status |
| 1 | GND |
|  | GND |

${ }^{1)}$ The pin assignments of X3 depend on the position of switches 3 and 4 of DIP switch S1.
Dimensional drawing and connection information


| Connection |  |
| :--- | :--- |
| Nr. | Function |
| X1, X2 | Motor connector |
| X3 | RS232 / CAN |
| X4 | Supply connector; I/O |
|  |  |
| Nr. | Switch |
| S1 | DIP-switch (6 switches) |

